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Example for method of feasible direction. 130 7. Linear and Nonlinear Programming By Eq. (7.20)  $x_2 = 1 - x_1 + (1)A$ ,  $x_2^2 = x_1^2 + (1)A$  The constraint equations are used to establish the maximum distance of movement, because  $f$  increases continuously as  $i$  increases. Thus a Fibonacci search is unnecessary. Since  $f_2 = (x_1' - 4 - A)(x_2' + A)$  then By Eq.

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geometric representation. Chapter 10 applies the concepts developed before to the linear production model in economics. To this end we use, particularly, Perron- Frobenius Theorem. Chapter 11 deals with the notion of convexity, and so-called separation theorems. We use this instrument to analyse the linear programming problem.

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